

**BRIEF PAPER**

**ASYMPTOTIC METHOD FOR SOLUTION OF THE OPTIMIZATION  
PROBLEM WITH PERIODIC BOUNDARY CONDITIONS AND CONTROL  
IN GASLIFT PROCESS**

I.M. ASKEROV<sup>1</sup>, N.A. ISMAILOV<sup>1</sup>

ABSTRACT. In this paper the asymptotic method of solving the periodic boundary optimal control problem in gaslift is given. An example is presented to illustrate the obtained results.

Keywords: optimal control, asymptotic method, gaslift process.

AMS Subject Classification: 49J15, 49M25, 49N10.

1. INTRODUCTION

In this work, the periodic boundary optimal control problem for the low-loss transmission of the mixture from the well bottom in the exploitation of the oil wells by gaslift method is considered [6]. Solution of this problem with periodic boundary condition using the asymptotic method is investigated and the solution algorithm is given to this problem [1, 2, 7]. The results are illustrated by example from practice.

2. PROBLEM STATEMENT

If to average small parameter describing lifting and movement of the gas and gas-liquid mixture in the ring-shaped space in the gas lift process on over the time [2, 5] then in the mathematical model we have the following non-linear differential equation

$$\dot{Q}(x, \mu) = \frac{2a\rho F Q^2(x, \mu)}{\mu c^2 \rho^2 F^2 - Q^2(x, \mu)}, Q(0, \mu) = u_0(\mu) = u_0^{(0)} + \mu \cdot u_0^{(1)} + \dots, \quad (1)$$

here  $a = \frac{g}{2\omega_c} + \frac{\lambda_c \omega_c}{4D}$ ;  $c$  is the sound speed;  $\omega_c$  - speed of the mixture movement;  $\rho$ - gas density;  $\lambda_c$ -hydraulic resistance;  $g$ -free fall acceleration;  $F$ - effective area of the ring-shaped space and lift;  $\mu = \varepsilon^2$ - small parameter ;  $\varepsilon = \frac{1}{2l}$ ;  $l$ - depth of the well and  $u$ - volume of injected gas. According to (2) we regulated the system by using the start control. The equation (1) due to coefficients  $(a_1, \rho_1, F_1, c_1)$  and  $(a_2, \rho_2, F_2, c_2)$  in the segments  $0 \leq x \leq \frac{1}{2} - 0$  and  $\frac{1}{2} + 0 \leq x \leq 1$  correspondently transforms into two different equations. These two equations are related to each other by following impuls system at the point  $\frac{1}{2}$

$$Q(\frac{1}{2} + 0, \mu) = \gamma Q(\frac{1}{2} - 0, \mu) + (-\delta_3(Q(\frac{1}{2} - 0, \mu)) - \delta_2)^2 + \delta_1) \bar{Q}, \quad (2)$$

<sup>1</sup>Institute of Applied Mathematics, Baku State University, Baku, Azerbaijan,  
e-mail: lidrak378@rambler.ru, inao212@rambler.ru

*Manuscript received July, 2013.*

where  $\gamma, \delta_1, \delta_2, \delta_3$  are positive real numbers defined as in [2].

Here our aim is to make equal the volume of lifting GLM in the well bottom to its volume in the wellhead by injecting minimal gas [1]. Therefore, we add the following periodicity condition [4, 6]:

$$Q\left(\frac{1}{2} + 0, \mu\right) = Q(1, \mu). \quad (3)$$

It is clear that this is not possible in practice. Therefore we take the condition (3) in the following form

$$Q\left(\frac{1}{2} + 0, \mu\right) = \tau \cdot Q(1, \mu), \quad (4)$$

here  $\tau$  is a positive real number in  $0 < \tau < 1$ . It is possible to achieve our aim by tending this parameter to 1. Thus, the problem consists of finding an initial gas volume  $Q(0)$ , which satisfies the conditions (1), (2) and minimizes the following function

$$J = \frac{1}{2}\alpha Q^2\left(\frac{1}{2}, \mu\right) + \beta u^2(\mu), \quad (5)$$

where  $\alpha < 0$  and  $\beta > 0$  are real numbers.

For the solving of the problem the extended functional is written and then we get the Euler-Lagrange equation [3]

$$\dot{\lambda}(x, \mu) = -\frac{4ac^2\rho^3F^3Q(x, \mu) \cdot \mu}{(\mu c^2\rho^2F^2 - Q^2(x, \mu))^2}\lambda(x, \mu) \quad (6)$$

and the following boundary conditions

$$\begin{aligned} \alpha Q\left(\frac{1}{2} + 0, \mu\right) + \left(\frac{\beta}{2} - 1\right) \cdot \lambda\left(\frac{1}{2} + 0, \mu\right) - \frac{\beta}{2} \cdot \lambda(1) &= 0, \\ \gamma\lambda\left(\frac{1}{2} + 0, \mu\right) - \frac{\beta}{2}\lambda\left(\frac{1}{2} - 0, \mu\right) - 2\delta_3\lambda\left(\frac{1}{2} + 0, \mu\right)(Q\left(\frac{1}{2} - 0, \mu\right) - \delta_2)\bar{Q} &= 0, \\ u(\mu) + \frac{\beta}{2}\lambda(0) + \delta(\mu) &= 0, \end{aligned} \quad (7)$$

where  $\lambda(x)$  and  $\delta$  are Lagrange multipliers. We search the solutions of the equations (1) and (6) in the form of following series

$$Q(x, \mu) = Q^{(0)}(x) + \mu Q^{(1)}(x) + \mu \frac{Q^{(2)}(x)}{2!} + \dots, \quad (8)$$

$$\lambda(x, \mu) = \lambda^{(0)}(x) + \mu\lambda^{(1)}(x) + \mu \frac{\lambda^{(2)}(x)}{2!} + \dots, \quad (9)$$

and  $\delta(\mu) = \delta^0 + \mu \cdot \delta^1 + \dots$ .

If to take into account these solutions in the equations (1) and (6) we obtain the following differential equations in the first approach

$$\begin{aligned} \dot{Q}^{(0)}(x) &= -2a\rho F, \quad Q^{(0)}(0) = u_0^{(0)}, \\ \dot{Q}^{(1)}(x) &= -\frac{2a\rho^3F^3c^2}{Q^{(0)2}(x)}, \quad Q^{(1)}(0) = u_0^{(1)}, \dots, \\ \dot{\lambda}^{(0)}(x) &= 0, \quad \dot{\lambda}^{(1)}(x) = -4c^2a\rho^3F^2Q^0(x) \cdot \lambda^0(x), \dots \end{aligned} \quad (10)$$

Considering (8) and (9) in (7) the similar representations may be obtained for

$Q^{(i)}(0), \lambda^{(i)}(0), Q^{(i)}(\frac{1}{2} - 0), \lambda^{(i)}(\frac{1}{2} - 0), \lambda^{(i)}(\frac{1}{2} + 0), Q^{(i)}(\frac{1}{2} + 0), \lambda^{(i)}(1), Q^{(i)}(1)$  and  $\delta^i \ i = 0, 1, \dots$ . If to linearize the conditions (7), then we obtain the following system of linear algebraic equations, which depends on the above variables

$$K_1 Z_1 = q_1, K_2 Z_2 = q_2, \tag{11}$$

where

$$Z_1 = \left[ Q^{(0)}(0), \lambda^{(0)}(0), Q^{(0)}(\frac{1}{2} - 0), \lambda^{(0)}(\frac{1}{2} - 0), Q^{(0)}(\frac{1}{2} + 0), \lambda^{(0)}(\frac{1}{2} + 0), Q^{(0)}(1), \lambda^{(0)}(1), \delta^0 \right]^T,$$

$$K_1 = \begin{bmatrix} 0 & 0 & -(\gamma + 2\delta_3\delta_2\bar{Q}) & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \alpha & -1 & 0 & 0 & 0 \\ 0 & 0 & -2\delta_3\bar{Q} & 0 & 0 & \gamma & 0 & 0 & 0 \\ 1 & \frac{\beta}{2} & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & -\tau & 0 \end{bmatrix},$$

$$q_1 = [\delta_1\bar{Q} - 2\delta_3\delta_2^2\bar{Q}, 0, 0, -\delta, -a_1\rho_1F_1, 0, -a_2\rho_2F_2, 0, 0]^T,$$

$$K_2 = \begin{bmatrix} 0 & 0 & -2\delta_3\bar{Q}(Q^{(0)}(\frac{1}{2}) - \delta_2) & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & \alpha & \frac{\beta}{2} & 0 & 0 & 0 \\ 0 & 0 & -2\delta_3\bar{Q}\lambda^{(0)}(\frac{1}{2} + 0) & 0 & 0 & p & 0 & 0 & 0 \\ 1 & \frac{\beta}{2} & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & -\tau & 0 \\ -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix},$$

$$Z_2 = \left[ Q^{(1)}(0), \lambda^{(1)}(0), Q^{(1)}(\frac{1}{2} - 0), \lambda^{(1)}(\frac{1}{2} - 0), Q^{(1)}(\frac{1}{2} + 0), \lambda^{(1)}(\frac{1}{2} + 0), Q^{(1)}(1), \lambda^{(1)}(1), \delta^1 \right]^T,$$

$$q_2 = \left[ 0, \frac{\beta}{2}\lambda^{(0)}(1), \frac{\beta}{2}\lambda^{(0)}(\frac{1}{2} - 0), 0, S, M, 0, W, G \right]^T$$

and ‘T’ is the operation of transpose.

Here

$$p = 1 - 2\delta_3Q^{(0)}(\frac{1}{2} - 0)\bar{Q}, \quad S = -\frac{2a_2\rho_2^3F_2^3c_2^2}{Q^{(0)2}(1)} + \frac{a_2\rho_2^3F_2^3c_2^2}{Q^{(0)2}(\frac{1}{2} + 0)},$$

$$M = -4c_2^2a_2\rho_2^3F_2^2Q^{(0)}(1) \cdot \lambda^{(0)}(1) + 2c_2^2a_2\rho_2^3F_2^2Q^{(0)}(\frac{1}{2} + 0) \cdot \lambda^{(0)}(\frac{1}{2} + 0)$$

$$W = -\frac{a_1 \rho_1^3 F_1^3 c_1^2}{Q^{(0)2} \left(\frac{1}{2} - 0\right)}, \quad G = -2c_1^2 a_1 \rho_1^3 F_1^2 Q^{(0)} \left(\frac{1}{2} - 0\right) \cdot \lambda^{(0)} \left(\frac{1}{2} - 0\right).$$

If to take into account the last solutions  $Q^{(0)}(0)$ ,  $Q^{(1)}(0)$  found from (11) we can find the first approximation for the solutions  $u \approx Q^{(0)}(0) + \mu \cdot Q^{(1)}(0)$  of the problem (1), (2), (5). The following algorithm is proposed for the solution of periodic problem by the asymptotical method.

### 3. ALGORITHM

- **Step 1.** Introduce the parameters  $a, \rho, F, c, l$  according to the intervals  $0 < x < \frac{1}{2} - 0$  and  $\frac{1}{2} + 0 < x < 1$
- **Step 2.** Input the matrices  $K_1, K_2$  and the column vectors  $q_1, q_2$  from (11).
- **Step 3.** Find  $Q^{(0)}(0)$  and  $Q^{(1)}(0)$  by solving the matrix algebraic equations  $K_1 Z_1 = q_1$  and  $K_2 Z_2 = q_2$  and define  $Q(0) \approx Q^{(0)}(0) + \mu \cdot Q^{(1)}(0) + \dots$
- **Step 4.** Define  $Q^{(0)}(x)$ ,  $Q^{(1)}(x)$  from (11) and reconstruct  $Q(x) \approx Q^{(0)}(x) + \mu \cdot Q^{(1)}(x) + \dots$

Now we take the above parameters to calculate the corresponding and  $Q(1, \mu)$  on the basis of the proposed algorithm with the optimal  $Q(0)$  as  $Q(l + 0, \mu) = 9,9231$ ,

Here is the plot of these calculations.

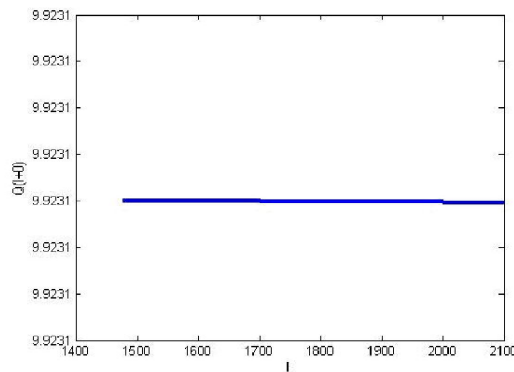


Fig. 1. Dependence of the mixture on the depth.

We see from the figure and the calculations that is 94.2518 % from . Thus, the model given in the work, allows one to lift the mixture from the well bottom to the wellhead 46% is increased to 94% as a implementation of the proposed model.

### REFERENCES

- [1] Aliev, F.A., (2011), Minimax solution of the searching problem of optimal regimes of gas lift, Reports of NAS of Azerbaijan, LXVII(1), pp.27-36
- [2] Aliev, F.A., Ismailov, N.A., (2013), An algorithm for constructing optimal regimes of the gas-lift process with minimum loss of lift production rate, Reports of NAS of Azerbaijan, LXIX(2), pp.306-313 (in Russian).
- [3] Bryson, A., Ho-Yu-Chi, (1969), Applied Optimal Control: Optimization, Estimation and Control, Woltham, Massachuselts, Blaisdel.
- [4] Colaneri, P., (2004), Periodic control systems: theoretical aspects, Appl. And Computer. Math., 3(2), pp.84-94.
- [5] Camponogara, Eduardo, Plusenio, Agustinho, Alex F., Teixeira, Sthener R.V.Campos, (2010), An automation system for gas-lifted oil wells: Model identification, control and optimization. // Journal of Petroleum Science and Engineering. 70, pp.157-167
- [6] Larin, V.B., (1978), Optimization of the periodic system, Dokl. A.N. SSSR, 239(1), pp.67-70 (in Russian).

- [7] Mirzajanzadeh, A. Kh., Akhmetov, I. M., Khasaev, A. M., Gusev, V. I., (1986), Technology and Techniques of Oil Extraction, M., Nedra, 382p. (in Russian).
- 



**Idrak Askerov** graduated from the Mechanical-Mathematical faculty of Baku State University in 2006. In 2009 he got M.S. degree from the same University. Since 2009 he is with the Institute of Applied Mathematics, Baku State University. His current research interests include numerical methods of control and optimization.



**Navazi Ismailov** graduated from Baku State University in 1980. He got Ph.D. degree from the Institute of Cybernetics of ANAS. His current research interests are in the areas of applied mathematics, system theory, control and numerical analysis. He is author /co-author more than 50 scientific papers.